

"CLASSIFYING" LIE ALGEBRAS

Lecture 6

including: Roots and weights etc.

[Knapp: Lie Groups Beyond an Introduction, I.5-I.8, II.1-II.5]

[Laksh-Brown Chap 7]

Lie algebras: Recall ideal \approx normal subgroup (think "normal subgr")

abelian: $[x,y] = 0 \quad \forall x,y$
solvable: inductively built from abelian ones...

semisimple: no solvable ideals (except $\{0\}$)

simple: no ideals at all (except $\{0\}$).

Ex. $\mathfrak{b} = \left\{ \begin{pmatrix} * & \dots & * \\ \vdots & & \vdots \\ 0 & \dots & * \end{pmatrix} \right\}$ solvable as $[\mathfrak{b}, \mathfrak{b}] = \begin{pmatrix} 0 & * & * \\ \vdots & & \vdots \\ 0 & & 0 \end{pmatrix}$ $[D\mathfrak{b}, D\mathfrak{b}] = \begin{pmatrix} 0 & 0 & * \\ \vdots & & \vdots \\ 0 & & 0 \end{pmatrix}$

Ex. $\mathfrak{gl}_n(\mathbb{C}) = \left\{ \begin{pmatrix} * \\ \vdots \\ * \end{pmatrix} \right\}$ is not semisimple. $\{cI_{n \times n}, c \in \mathbb{C}\}$ is a nonzero abelian ideal (in particular solvable).
 $\mathfrak{gl}_n(\mathbb{R}) =$

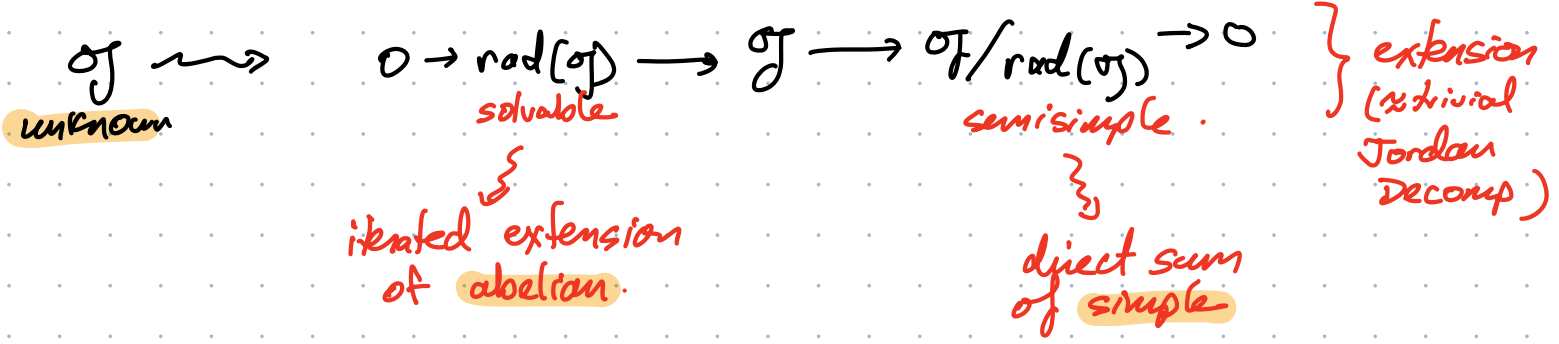
Exercise: $\mathfrak{sl}_n(\mathbb{C}), \mathfrak{sl}_n(\mathbb{R})$ are simple. ($\mathfrak{sl}_n(\mathbb{C}) = \left\{ \begin{pmatrix} * \\ \vdots \\ * \end{pmatrix} \in \mathfrak{gl}_n(\mathbb{C}) \mid \text{trace} = 0 \right\}$)

Theorem: semisimple \Leftrightarrow direct sum of simple.

Pf. See Knapp.

Ideals or cosets mean $\mathfrak{g}/\mathfrak{a}$ inherits a Lie bracket (like G/N group!)

So the overall idea is to understand Lie alg as:



So an understanding of simple ones, abelian ones, and extensions would suffice.

Simple Lie algs over \mathbb{C} admit a beautiful classification
(W. Killing 1890, E. Cartan 1894)

Idea: Take of apart and recognize canonical "pieces". The classification is in terms of the combinatorics of how they fit together.

It's a little complicated so let's do all the steps for $\mathfrak{sl}_n \mathbb{C}$ first.

Let $\mathfrak{g} = \mathfrak{sl}_n \mathbb{C} = \{ \text{traceless } n \times n \text{ complex matrices w/ commutator} \}$

Let $\mathfrak{h} = \{ \text{diagonal matrices in } \mathfrak{g} \}$

$\mathfrak{a} = \{ \text{real diag matrices in } \mathfrak{g} \}$

as Lie alg!

so: $\underbrace{\mathfrak{a} \subset \mathfrak{h} \subset \mathfrak{g}}_{\text{abelian}}$ subalgebras, also $\mathfrak{h} = \mathfrak{a} \oplus i\mathfrak{a}$.

Thus \mathfrak{h} is the Lie algebra complexification of \mathfrak{a} , $\mathfrak{h} = (\mathfrak{a})^{\mathbb{C}}$ or equivalently we say \mathfrak{a} is a real form of \mathfrak{h} .

Given $x \in \mathfrak{g}$, we get a linear map $\text{ad}_x: \mathfrak{g} \rightarrow \mathfrak{g}$ by $y \mapsto [x, y]$. } adjoint action of x

Now if $t \in \mathfrak{h}$, ad_t is diagonalizable, and a basis that diagonalizes it is:

E_{ij} = matrix w/ 1 in (i, j) else zero. ($\in \mathfrak{h}$ iff $i=j$)

Then we can make a basis of \mathfrak{g} from one of \mathfrak{h} plus $\{ E_{ij} \mid i \neq j \}$.

$\text{ad}_t(E_{ij}) = (t_i - t_j)E_{ij}$ as one can check, if $t = \begin{pmatrix} t_1 & & \\ & \dots & \\ & & t_n \end{pmatrix}$

So no matter what t is, $\{ E_{ij} \} + \text{basis of } \mathfrak{h}$ gives a basis of eigenvectors. But to say what the eigenvalue is, you need to know t .

But the map (element $t \in \mathfrak{h}_\mathbb{R}$) \mapsto (the eigenval of ad_t on E_{ij}) is linear, so it defines an element of $\mathfrak{h}_\mathbb{R}^* = \text{Hom}(\mathfrak{h}_\mathbb{R}, \mathbb{C})$

Def. An eigenvector of ad_t w/ eigenvalue $\lambda \in \mathfrak{h}_\mathbb{R}^*$ means a vector $x \in \mathfrak{g}$ s.t.

$$\text{ad}_t(x) = \underbrace{\lambda(t)}_{\text{in } \mathbb{C}} x$$

$\mathfrak{h}_\mathbb{R}$

But those names are not used. They would make too much sense. Instead:

Def. $x \in \mathfrak{g}^{-\{\theta\}}$ is called a weight vector with weight $\lambda \in \mathfrak{h}_\mathbb{R}^* - \{\theta\}$ if $\text{ad}_t(x) = \lambda(t)x \quad \forall t \in \mathfrak{h}_\mathbb{R}$.

Let $e_i \in \mathfrak{h}_\mathbb{R}^*$ be the map $(t_1, \dots, t_n) \mapsto t_i$

Then E_{ij} is a weight vector with weight $e_i - e_j$.

Def. The weights that occur for weight vectors in \mathfrak{g} (the "spectrum" of $\mathfrak{h}_\mathbb{R}$ on \mathfrak{g}) are called roots.

The roots of $\mathfrak{g} = \mathfrak{sl}_n \mathbb{C}$ are $\{e_i - e_j \mid i \neq j\} = \Phi \subset \mathfrak{h}_\mathbb{R}^*$

Thus $\mathfrak{g} = \mathfrak{h}_\mathbb{R} \oplus \bigoplus_{i \neq j} \mathfrak{g}_{e_i - e_j}$ where \mathfrak{g}_α is set of all weight vectors for $\alpha \in \mathfrak{h}_\mathbb{R}^*$.

\downarrow \downarrow
 $\begin{pmatrix} * & & * \\ & * & \\ & & * \end{pmatrix}$ $\mathbb{C} \cdot E_{ij}$
 $\begin{pmatrix} \dots & * \\ & \vdots \end{pmatrix}$

root space decomposition

Note Φ spans $\mathfrak{h}_\mathbb{R}^*$ over \mathbb{C} .

Nice property: $[\mathfrak{g}_\alpha, \mathfrak{g}_\beta] = \begin{cases} \mathfrak{g}_{\alpha+\beta} & \text{if } \alpha+\beta \in \Phi \\ \{0\} & \text{if } \alpha+\beta \notin \Phi, \text{ is not } 0 \\ \mathfrak{h}_\mathbb{R} & \text{if } \alpha+\beta=0. \end{cases}$

Ex. $n=3$: $\left[\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right] = 0$ as $2e_1 - e_2 - e_3$ not root

$$\left[\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$e_1 - e_2$ $e_2 - e_1$ in \mathfrak{h}

$$\left[\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \right] = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \alpha + \beta \in \Phi.$$

$e_1 - e_2$ $e_2 - e_3$ $e_1 - e_3$.

On \mathcal{O} , each root is \mathbb{R} -valued, and restr to \mathcal{O} determines it.

So $\alpha \in \Phi$ can be considered as elt of $\mathfrak{h}_\mathbb{C}^* = \text{Hom}(\mathfrak{h}_\mathbb{C}, \mathbb{C})$
OR elt of $\mathcal{O}^* = \text{Hom}(\mathcal{O}, \mathbb{R})$

Now we want to introduce a notion of positivity on \mathcal{O}^* , s.d.

① IF $\varphi \in \mathcal{O}^*$ is nonzero, one of $\varphi, -\varphi$ is positive (exactly one!)

② The set of positive elts is closed under $+$ and \mathbb{R}^+ -mult.

$$\mathcal{O}^* = \text{Hom}(\mathcal{O}, \mathbb{R}) = \text{Hom}(\{(t_1, \dots, t_n) \mid \sum t_i = 0\}, \mathbb{R}) \quad \sigma(t_1, \dots, t_n) = \sum t_i$$

$$= \text{Hom}(\ker \sigma, \mathbb{R})$$

$$= (\mathbb{R}^n)^* / \text{span } \sigma$$

i.e. $\mathcal{O}^* = \text{span}(e_1, \dots, e_n)$ but they're not quite indep
as $e_1 + \dots + e_n = \sigma$ which is zero on \mathcal{O} .

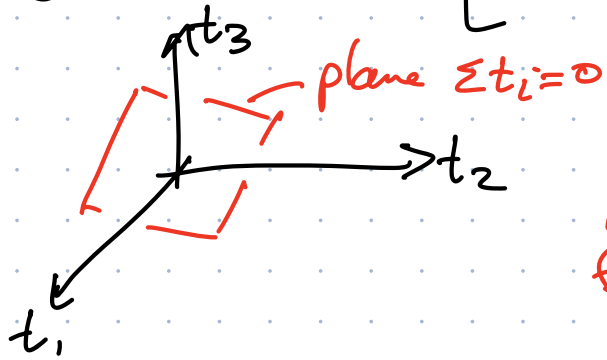
But any element of \mathcal{O}^* can be uniquely rep as $\sum a_i e_i$
where $\sum a_i = 0$.

e.g. $e_1 = \frac{2}{3}e_1 - \frac{1}{3}e_2 - \frac{1}{3}e_3$ on $\mathcal{O} \subset \mathfrak{sl}_3\mathbb{C}$.

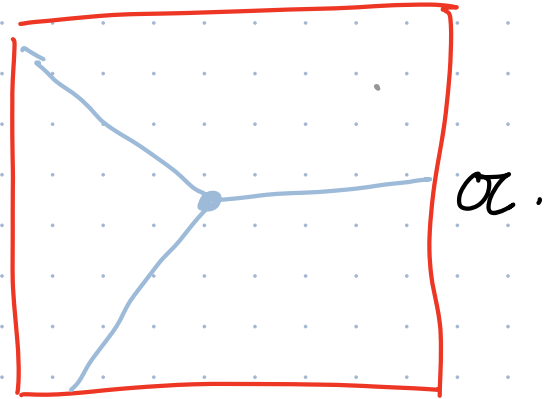
So let's say $\varphi \in \mathcal{O}^*$ is positive in this case if $\varphi = \sum a_i e_i$ with $\sum a_i = 0$ and the first nonzero coef a_k is positive (i.e. φ is "lexicographically greater than zero").

Let's try to make a picture.

$$\mathcal{O} = \mathfrak{sl}_3 \mathbb{C} \quad \mathcal{O} = \left\{ \begin{pmatrix} t_1 & & \\ & t_1 & \\ & & t_3 \end{pmatrix} \mid \sum t_i = 0 \right\} \subset \mathbb{R}^3.$$

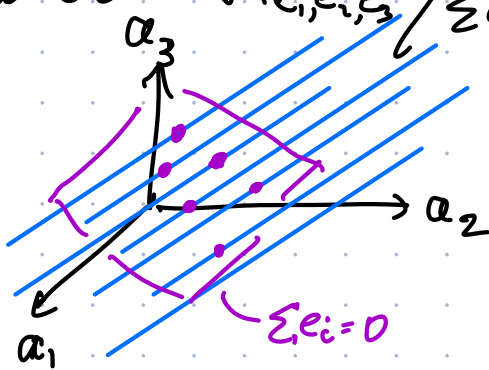


Look at it from huge $(1,1,1)$



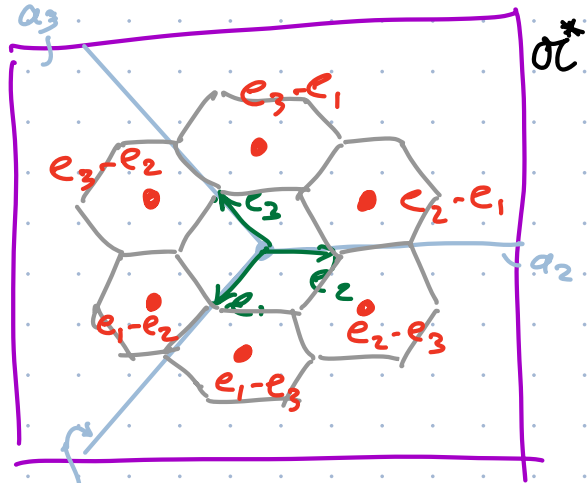
shadow t_1 axis

Now $\mathcal{O}^* = \mathbb{R}^3_{e_1, e_2, e_3} / \sum e_i$

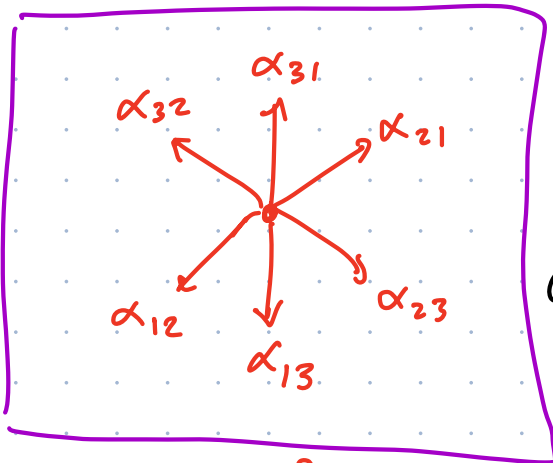


$\sum a_i e_i$ generic

intersect any translate of $\text{span}(e_1 + e_2 + e_3)$ w/ $\sum a_i = 0$.



shadow of a_1 axis



simplified drawing

\mathcal{O}^*

Roots of $\mathfrak{sl}_3 \mathbb{C}$

Exercise: Shade the positive region!